

# Lecture 7:

## Monitoring and enforcement

- Purpose
  - ▶ demonstrate why monitoring and enforcement (M&E) generally is necessary
  - ▶ understand the objective of M&E: to create desired compliance at least social costs
  - ▶ understand the impact of stochastic emissions
  - ▶ increase insights through some models of M&E

Eirik Romstad

School of Economics and Business  
Norwegian University of Life Sciences

<http://www.nmbu.no/hh/>



1:18

## Outline

- why is M&E important
  - ▶ for (emission) taxes to work
  - ▶ for tradable (emission) permits to work
- purpose of M&E
- stochastic emissions
- the penalty function
- basic model of M&E
- reputation based M&E schemes
- deviations reported and actual performance

2:18

## The importance of M&E

- Taxes
  - ▶ without M&E, firms may emit more than they should
    - optimal emission levels are exceeded
- Tradable permits
  - ▶ without M&E, firms may emit more than they should
    - optimal emission levels are exceeded
    - the prices (the info. extracting device of TPs) do not correspond to firms'  $MAC_i(z_i)$

3:18

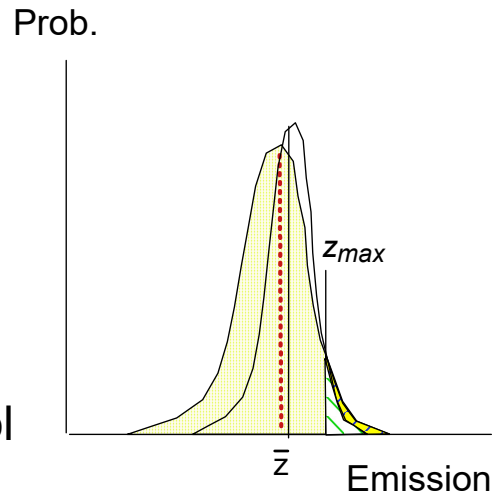
## The purpose of M&E

- Deliver the desired level of compliance at the least social costs
- Why desired compliance level rarely is 100:
  - ▶ the expected gains of M&E should equal the expected costs
- Why least cost is important:
  - ▶ does not hold: society spends more resources on M&E than it should
  - ▶ least costs implies that the optimal compliance level increases (why?)

4:18

## Stochastic emissions

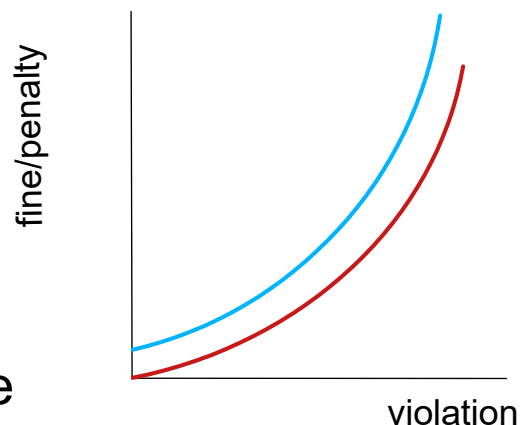
- Emissions generally not fixed, but stochastic
- Sources of stochasticity
  - ▶ measurement errors
  - ▶ natural processes are random (weather!)
  - ▶ insufficient process control
- Stochastic emissions
  - ▶ agents: safety interval (measurement error also triggers justification for safety interval)
  - ▶ increased process control  $\Rightarrow$  size of "needed" safety interval  $\downarrow \Rightarrow$  agents mean emissions  $\uparrow$



5:18

## The penalty function

- From welfare perspective
  - ▶ large violations of allowed emissions worse than small violations
  - ▶ increase penalty in size of violation
- Penalty
  - ▶ grows at an increasing rate in terms of the size of the violation
- Extra cost of (administering) a violation + grace = fixed term in the penalty function



6:18

## Basic model of M&E (1)

- Intuition:

- ▶ expected payoff of compliance  $\geq$  expected payoff of not complying
- ▶  $\pi_C$  = state dependent payoff of compliance
- ▶  $\pi_N$  = state dependent payoff of non-compliance
- ▶  $S$  = penalty if found in non-compliance

$$\rho \pi_C + (1 - \rho) \pi_C \geq \rho (\pi_N - S) + (1 - \rho) \pi_N$$

$$\pi_C \geq \rho \pi_N - \rho S + \pi_N - \rho \pi_N$$

$$\rho \geq \frac{\pi_N - \pi_C}{S}$$

7:18

## ... basic model of M&E (2)

- Addition of stochastic emissions

- ▶ allow some grace region, like  $k$ , which allows extra emissions over the limit for compliance

$$\rho \geq \frac{\pi_N - \pi_C}{S(z - k)}$$

- Principal's problem

- ▶ make  $k$  sufficiently large to avoid that overcompliance is not too large
- ▶ to adjust (reduce)  $k$  over time as agents increase their precision

8:18

## Reputation based M&E

- **Intuition:** monitoring probabilities and penalties depend on past performance creates a compliance rent that reduces the monitoring prob. needed for incentive compatibility to hold
- **Basic setup:**
  - ▶ group 3 (habitual non compliers): pay monitoring costs themselves and must comply in repeated periods before being moved to **group 2**
  - ▶ group 2: lower monitoring prob. than group 3 firms, and must comply to get to **group 1**
  - ▶ group 1 (habitual compliers) have the lowest monitoring prob and do not pay monit.costs

9:18

## ... reputation based M&E (2)

- Monitoring probabilities:
  1. habitual compliers (monitoring prob =  $p_1$ )
  2. in the "purgatory" (monitoring prob =  $p_2$ )
  3. "habitual" cheaters (monitoring prob =  $p_3$ )
  - ▶  $p_1 < p_2 < p_3 \leq 1$
- Monitoring costs:
  - ▶ group 3 firms pay monitoring costs themselves
  - ▶ group 1 and 2 firms do not pay monitoring costs

10:18

## ... reputation based M&E (3)

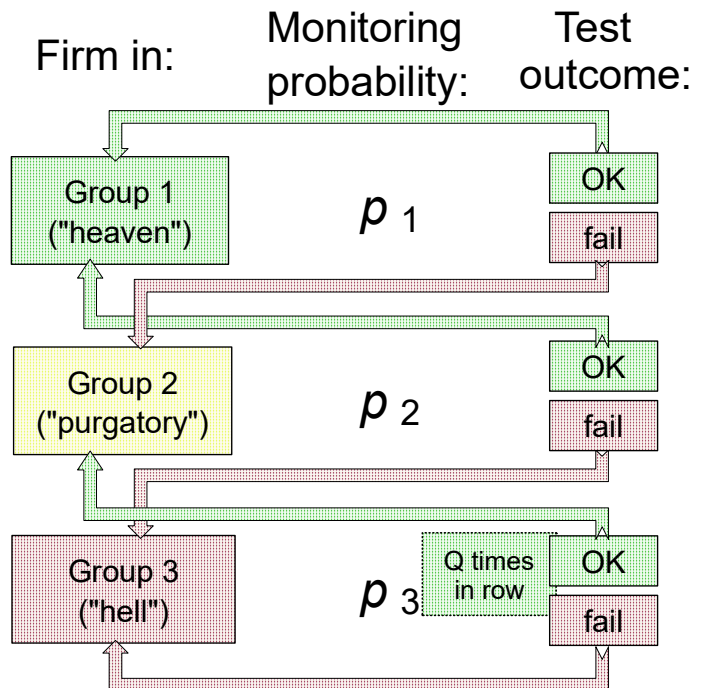
Structure:

### *implementation*

(before firms have established a reputation): depends on firm mobility

### *fully operational*

- ▶ existing firms moved to group matching reputation
- ▶ entrant firms start in group 3 (or group 2)



10:18

## ... reputation based M&E (4)

### ● Intuition behind the scheme

- ▶ **compliance rent** (= extra rents-/profits  $\leftarrow$  from past compliance)  $\Rightarrow$ 
  - ➔ lower monitoring probability (habit of compliance  $\Rightarrow p_i \downarrow$ )
  - ➔ stronger incentive for compliance than under uniform monitoring
- ▶ lower overall effort spent on monitoring by the regulator  $\Rightarrow$  lower social costs of monitoring
- ▶ participation constraint OK for complying firms (firm at least as well off in reputation model than in uniform monitoring)

12:18

## ... reputation based M&E (5)

- Group 3 firms pay monitoring costs,  $M$ 
  - ▶ can be justified as they have ended up in group 3 due to their own failure to comply
  - ▶ reduces profits in group 3 by  $\rho_3 M$
  - ▶ creates an extra incentive to avoid group 2 and 3 ==> lowers monitoring probs. for group 1 and 2
- Group 3 monitoring probability equal to basic equation monitoring probability:

$$\rho_3 = \frac{\pi_N - \pi_C}{S}$$

- We get:  $\rho_1 < \rho_2 < \rho_3$

13:18

## ... reputation based M&E (6)

Net present value of compliance costs in group 2:

group 2 **OK** where  $c = \pi_N - \pi_C$

$$\sum_{t=0}^{T_2+1+QT_3} \beta^t (p_2 s - c) <$$

$$\sum_{t=0}^{T_2} \beta_{T_2} s + \sum_{t=T_2+1}^{T_2+1+QT_3} \beta^t (p_3 s - c + p_3 m)$$

group 2 **not OK**      group 3 **OK**

↑  
caught in  
group 2

$T_i$  is expected time in group  $i$   
 $\beta$  is the discount factor  $(1+r)^{-1}$

14:18

## ... reputation based M&E (7)

Net present value of compliance costs in group 1:

group 1 **OK** where  $c = \pi_N - \pi_C$

$$\sum_{t=0}^{T_1+1+T_2} \beta^t (p_1 s - c) <$$

$$\sum_{t=0}^{T_1} \beta^{T_1} s + \sum_{t=T_1+1}^{T_1+1+T_2} \beta^t (p_2 s - c)$$

group 1  
not **OK**

↑  
caught in  
group 1

group 2 **OK**

$T_i$  is expected time in group  $i$   
 $\beta$  is the discount factor  $(1+r)^{-1}$

15:18

## Deviation: reports and actions (1)

- Starting point:
  - ▶ firms self-report, and regulator performs checks
  - ▶ single sectors/firms are informed that next year their behavior/actions will be heavily monitored
- Intuitive results:
  - ▶ firms that reported truthfully  
no change in behavior/actions
  - ▶ firms that reported false (doomed if you do, doomed if you don't):
    - adjust behavior, but deviations from prev. years' reports ⇒ signal to regulator something wrong
    - do not adjust: one is caught:

16:18



## ... deviation: reports and actions (2)

- Implemented (in a systematic sense)
  - ▶ UK : tax audits for independent small firms (plumbers, carpenters, etc.)
  - ▶ no academic papers yet (as I know), but a promising approach
- Possible advantages
  - ▶ most firms self report (also on env. issues)  
⇒ no additional costs onto firms
  - ▶ reduces M&E costs (as in reputation base M&E) through targeting
  - ▶ can be implemented immediately as past self reports exists

17:18

## Summary

- Objective of monitoring and enforcement:  
create desired compliance at the least social costs
- Stochastic emission: "grace intervall" ( $k$ )
  - ▶ = extra incentives for firms to increase precision  
(reduce future  $k$  to avoid excessive mean emissions)
- Basic idea behind monitoring and enforcement:  
make the expected payoff of compliance larger than the expected payoff of noncompliance
  - ▶ basic model for M&E ::  $p \geq (\pi_N - \pi_C)/S$
  - ▶ extension 1: reputation based models
  - ▶ extension 2: deviation reports - actions

18:18